

# Types and Tuples in D

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$$\frac{\Gamma, T1 \ x \vdash e : T2}{\Gamma \vdash ((T1 \ x) \Rightarrow e) : T2} \text{ delegate}(T1) ?$$

`auto (x, (y, z)) = t;`



# What is this talk?

Originally proposed:

- ▶ Types in D. 45min talk.
- ▶ Tuples in D. 25min talk.

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⇒ **Types talk or tuples talk? Yes.**

Basically, I will freely associate about D's type system for hopefully  $\sim 45$  minutes. Disclaimer: We will look at some dark corners of the language. This is not a particularly representative sample of language rules. Here be dragons!

# What is a type?

- ▶ Metadata describing the (run-time) effect of an expression.
- ▶ Often classifies values for arguments/results. (e.g., `typeof(2*3)` is `int`)
- ▶ Often tracks side effects. (e.g., `pure @safe nothrow`)
- ▶ Sometimes prescribes *memory layout*.
- ▶ Information often partially or fully erased at runtime.

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$$(\lambda x. x x) (\lambda x. x x)$$

---

```
1   for (;;) {}  
2   while(true) {}
```

---

# Basic Types

---

```
1 short i = 1;  
2 int j = 2;  
3 float x = 3.0f;  
4 double y = 4.0;
```

---

# Value Range Propagation

D tracks an overapproximation of the range of any integral expression.

---

```
1  int k = 1;
2  short i = k; // error
3
4  short j = 1; // ok
5  static_assert(is(typeof(1) == int));
6
7  int a = ...;
8  ushort b = a; // error
9
10 ushort c = a & 0xffff; // ok
```

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Works using interval arithmetic.

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```

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Works using interval arithmetic.

Fun exercise: Deriving best transformers for bitwise operations.

# Type Constructors

---

```
1 int[] a = [1, 2, 3];
2 const(int)[] b = a;
3 immutable(int)[] c = [1, 2, 3];
4
5 a[0] = 2; // ok
6 assert(a == [2, 2, 3]);
7 assert(b == [2, 2, 3]);
8
9 b[0] = 3; // error
10 c[0] = 4; // error
11
12 b = c; // ok
```

---

```
1 int[3] c = [1, 2, 3];
2 int[int] d = [0:1, 1:2, 2:3]
```

---

# Type Constructors

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```

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```
1 int [3] c = [1, 2, 3];
2 int [int] d = [0:1, 1:2, 2:3]
```

---

Magic, users cannot define their own type constructors.



# Lvalues/Rvalues

Expressions can be lvalues or rvalues. Some types are meaningful only for lvalues:

---

```
1 enum n = cast(const)5;
2
3 pragma(msg, n); // 5
4 pragma(msg, typeof(n)); // const(int)
```

---

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```
1 enum n = cast(const)5;
2
3 pragma(msg, n); // 5
4 pragma(msg, typeof(n)); // const(int)
```

---

```
1 5 = 6; // error, 5 is rvalue
2
3 int m = n; // ok
4 m = 6; // ok, m is lvalue
5
6 int[] a = [n]; // ok (array literal magic)
7 assert(a[0] == 5);
8 a[0] = 6; // ok, a[0] is lvalue
```

---

# Storage Classes

Example:

---

```
1 immutable int x = 2;
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1 immutable { int x = 2; }
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What people think it means:

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1 (immutable int) x = 2;
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What it actually means:

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```
1 immutable { int x = 2; }
```

---

OTOH, this is allowed:

---

```
1 alias Int = immutable(int);  
2 alias Int = immutable int;  
3  
4 enum x = cast(immutable int)5;
```

---

## Storage classes (cont.)

---

```
1 immutable(int) x = 2; // storage class copied to variable
```

---

```
1 immutable int x = 2; // qualifier copied to type
```

---

```
1 immutable immutable(int) x = 2; // fully spelled out
```

---

# Functions: Storage classes

---

```
1 immutable int* foo(int* p) => p;
```

---

To untrained eye, may look like:

---

```
1 immutable(int*) foo(int *p) => p;
```

---

Actually means:

---

```
1 immutable { int* foo(int* p) => p; }
```

---

---

```
1 int* foo(int* p) immutable => p; // (qualifies context pointer)
```

---

Can throw off people, `ref` qualifies function, *in fact relates* to the return value.



# Functions: Storage classes

This is even the case for `ref`:

---

```
1 ref int foo(return ref int x) => x;
```

---

Is the same as:

---

```
1 ref { int foo(return ref int x) => x; }
```

---

---

```
1 int foo(return ref int x)ref => x;
```

---

Can throw off people, `ref` qualifies function, *in fact relates* to the return value.

## NB: ref on delegate types

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1 ref int foo(return ref int x) => x;  
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1 ref int delegate(return ref int) dg = x=>x; // nope
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Even though this works:

---

```
1 int foo(int x)immutable => x; // ok (if context exists)  
2 int delegate(int)immutable dg = x=>x; // ok
```

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## NB: ref on delegate types

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1 ref int foo(return ref int x) => x;  
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Need some movement on this.

# Functions: Overloading

The static type can actually determine which code runs at runtime.

---

```
1 void foo(int x){ ... }
2 void foo(int [] a){ ... }
3
4 foo(2);           // calls first overload
5 foo([1,2,3]);    // calls second overload
```

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The `const(int)` rvalue strikes back:

---

```
1 void foo(int x){ ... }
2 void foo(const(int) x){ ... }
3
4 foo(2);           // calls first overload
5 foo(cast(const)2); // calls second overload
```

---



## Fun fact: Template instantiation during overload resolution

---

```
1 void foo(int delegate(int) dg){ ... }
2 void foo(double delegate(double) dg){ ... }
3
4 foo((x){ pragma(msg, typeof(x)); return 2; }); // first overl.
```

---

```
1 int
2 double
```

---

# Type deduction

---

```
1 auto x = 2; // type left out, inferred as 'int x = 2;'
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- ▶ Actually: `auto` is just needed here to introduce a declaration.

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- ▶ Actually: `auto` is just needed here to introduce a declaration.
- ▶ (`x=2;` would be an assignment to an existing `x`.)

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```
1 const x = 2; // type left out, inferred as 'const int x = 2;'
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- ▶ Actually: `auto` is just needed here to introduce a declaration.
- ▶ (`x=2;` would be an assignment to an existing `x`.)

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```
1 const x = 2; // type left out, inferred as 'const int x = 2;'
```

---

NB: Another way a `const` rvalue may take effect:

---

```
1 auto x = cast(const)2; // inferred as 'const(int) x = ...;'
```

---



# Type deduction: Limitations

Only works forward:

---

```
1 auto x = [];  
2 x ~= 1; // error: cannot append 'int' to 'void[]'
```

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```
1 int[] x = [];  
2 x ~= 1; // ok
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1 auto x = [];  
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```

---

(NB: `typeof([])` should be `noreturn[]`.)

# Type deduction: Limitations

Can break code by returning more refined type instead:

---

```
1 class C{}
2 class D: C{}
3
4 C foo(){ ... }
5 C bar(){ ... }
6
7 void main(){
8     auto result = foo();
9     result = bar();
10 }
```

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# Desirable properties of type systems

- ▶ Simplicity
- ▶ Ergonomics (Readability/Writability)
- ▶ Expressiveness
- ▶ Conciseness
- ▶ Extendability
- ▶ Inference
- ▶ Good Diagnostics
- ▶ Orthogonality, no magic
- ▶ Modularity
- ▶ Separate compilation
- ▶ Type safety
- ▶ Fast type checking
- ▶ Compilation (Simple, fast, results in performant code)
- ▶ Eraseability
- ▶ Type-directed syntactic sugar

# Expressiveness tradeoffs

Pro:

- ▶ Code is more self-documenting.
- ▶ More metadata accessible by tooling.
- ▶ Detects errors more efficiently than tests would.

Con:

- ▶ Tests needed anyway.
- ▶ Can lead to annotation overhead.
- ▶ More likely to become non-modular.



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Keeping language simple throughout this evolution is challenging.

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Tendency to *evolve* from less expressive type systems to more expressive ones. Keeping language simple throughout this evolution is challenging. However, keep in mind, there *are* simple systems that are very expressive.

# Modularity

- ▶ Ability to factor out patterns into functions/aggregates.
- ▶ Type information must be able to cross function/aggregate boundaries.

# Example: Successful refactoring

---

```
1 void main(){  
2   int x = 2;  
3   int y = x+3;  
4   ...  
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```
1 void main(){
2   int x = 2;
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4   ...
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```

---

```
1 int f(int a, int b) => a + b;
2
3 void main(){
4   int x = 2;
5   int y = f(x,3);
6   ...
7 }
```

---

## Example: Unsuccessful refactoring

---

```
1 void main() {  
2     auto x = readln().strip.to!int;  
3     ubyte y = x & 0xff;  
4     ...  
5 }
```

---

## Example: Unsuccessful refactoring

---

```
1 void main() {
2     auto x = readln().strip.to!int;
3     ubyte y = x & 0xff;
4     ...
5 }
```

---

```
1 int mask_low(int x, int nbits) => x & ((1 << nbits) - 1);
2
3 void main() {
4     auto x = readln().strip.to!int;
5     ubyte y = mask_low(x, 8);
6     // error: cannot convert 'int' to 'ubyte'
7     ...
8 }
```

---



## Example: Unsuccessful refactoring

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Issue: No way to pass value ranges across function boundaries.

# Type safety

- ▶ Types define invariants on program state.
  - ▶ *safe* values.
  - ▶ aliasing constraints.
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- ▶ Types define invariants on program state.
  - ▶ *safe* values.
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  - ▶ ...
- ▶ Operations have defined behavior if invariants hold.
- ▶ Operations preserve invariants.

## Example: Violation of type safety

---

```
1 import std.stdio;
2
3 void main(){
4     bool b = void;
5     if(b){
6         writeln("b is true");
7     }
8     if(!b){
9         writeln("b is false");
10    }
11 }
```

---

# Type safety tradeoffs

Pro:

- ▶ Programs do not lie. Types act as compiler-checked documentation.
- ▶ Higher confidence in refactoring.
- ▶ Can support *safety guarantees*.

Con:

- ▶ Perfectly fine programs may be rejected.
- ▶ Leads to pressure to increase expressiveness and modularity.
- ▶ As a consequence, usually leads to higher annotation overhead.

# D's approach to type safety

Lack of type safety is essentially treated as a *side effect*.

- ▶ `@system`: Types are suggestions, programmers are infallible.
- ▶ `@trusted`: Type safe interface, programmer is infallible, caller is restricted but adversarial.
- ▶ `@safe`: Type safe. Programs have defined behavior, programmers are adversarial, callers are restricted but adversarial.

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Overall goal:

- ▶ Type safety and low-level control coexist in the same program.
- ▶ `@trusted` functions or the language are to blame for any holes in `@safe`.
- ▶ Introduces a sort of compile-time modularity for memory safety.
- ▶ Run-time effects of memory unsafety still unrestricted.



# Effect tracking for functions

D also prevents other side effects. E.g., function types have an *effect* annotation.

- ▶ `@safe`: no memory corruption / undefined behavior.
- ▶ `pure`: no mutation of global state (**mostly**)
- ▶ `nothrow`: no throwing of `Exception`.
- ▶ `@nogc`: no GC pauses, no GC allocation.

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- ▶ `@nogc`: no GC pauses, no GC allocation.

Other effects one could prevent (but D does not attempt to):

- ▶ Dynamic memory allocation
- ▶ Irreversibility
- ▶ Errors
- ▶ Nontermination
- ▶ ...

## Some practical challenges for D's effect tracking

- ▶ `pure` is underspecified. E.g., when can a function be `@trusted pure`?
- ▶ Often, people want to check their code non-transitively.
- ▶ `@trusted` is tricky to use correctly, hard to specify in a fine-grained way which operations one wants to trust, particularly in generic code.
- ▶ As a result, even the standard library uses `@trusted` lambdas with an unsafe interface. `((@trusted => cast(...)...))()`;
- ▶ Should probably be made more usable.

# NB: Inference and Defaults

Inference:

- ▶ `auto` return functions infer effects.
- ▶ Functions in template instances infer effects.
- ▶ Currently no other way to turn on inference if return type specified.
- ▶ Inference currently unreliable when there is mutual recursion.

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- ▶ DIP 1028 proposed making `@safe` the default.
- ▶ Ultimately retracted, because that's not a sane default for `extern(C)` function prototypes.

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Switching defaults:

- ▶ Currently there is no way to switch defaults without turning off inference.

# Effect tracking on lvalues

Type qualifiers restrict or enhance allowed effects taking place on their values.

- ▶ (unqualified) T: can be mutated, may not be shared
- ▶ `immutable`(T): cannot be mutated globally, can be shared freely
- ▶ `const`(T): cannot be mutated through current reference
- ▶ `inout`(T): wildcard, more later
- ▶ `shared`(T): may be shared, must properly synchronize access

Qualifiers are transitive. No mutation really means no mutation.

# Non-modularity of Effect Tracking

Challenge: Create a delegate that composes two `int delegate(int)`s:

---

```
1 alias ComposeType =
2   int delegate(int)
3     delegate(
4       int delegate(int),
5       int delegate(int),
6     )@safe pure nothrow;
7
8 ComposeType compose = (
9   int delegate(int) a,
10  int delegate(int) b,
11 )@safe pure nothrow{
12   return x=>a(b(x));
13 };
```

---



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3     delegate(
4       int delegate(int),
5       int delegate(int),
6     )@safe pure nothrow;
7
8 ComposeType compose = (
9   int delegate(int) a,
10  int delegate(int) b,
11 )@safe pure nothrow{
12   return x=>a(b(x));
13 };
```

---

Issue: No type of delegate can correctly preserve `@safe pure nothrow`.

# Non-modularity of Effect Tracking

Challenge: Create a delegate that composes two `int delegate(int)`s:

---

```
1 alias ComposeType =
2   int delegate(int)
3     delegate(
4       int delegate(int),
5       int delegate(int),
6     )@safe pure nothrow;
7
8 ComposeType compose = (
9   int delegate(int) a,
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11 )@safe pure nothrow{
12   return x=>a(b(x));
13 };
```

---

Issue: No type of delegate can correctly preserve `@safe pure nothrow`.

Pure *modularity* problem: if we inline `compose` into its callers, this works.

## Less contrived example: (virtual) opApply

---

```
1 class ASTNode{
2   int componentsImpl(scope int delegate(ASTNode) dg){
3     return dg(this);
4   }
5   auto components()return scope{
6     struct Components{
7       ASTNode self;
8       int opApply(scope int delegate(ASTNode) dg){
9         return self.componentsImpl(dg);
10      }
11    }
12    return Components(this);
13  }
14 }
```

- 
- ▶ Might reach for opApply, as ranges less well-suited for traversing a tree.
  - ▶ Supporting all combinations of qualifiers is a heavy burden on library authors.

## More contrived example: Identity function

---

```
1 int delegate(int) delegate(int delegate(int)) id = dg=>dg;
```

---

- ▶ Implementation above strips all function qualifiers.
- ▶ In practice can get relatively far with templated functions.

---

```
1     T id(T)(T dg)=>dg;
```

---

- ▶ Issue: It's either templates or virtual calls. :(
- ▶ Templates are usually the better option, even ignoring qualifiers. (IFTI does not match lambdas very reliably.)
- ▶ Leads to template bloat, larger compile times.

# This has happened before!

The same issue exists for the mutability qualifiers.

`inout` was invented to address this.

---

```
1 inout(int)* id(inout(int)* p) => p;
```

---

Replaces:

---

```
1 int* id(int* p) => p;  
2 const(int)* id(const(int)* p) => p;  
3 immutable(int)* id(immutable(int)* p) => p;
```

---

Plus, `&id` is a single virtual function.

# inout qualifier

Issue:

- ▶ There is only one `inout` qualifier.
- ▶ There can be multiple functions.
- ▶ Which function relates to which `inout` annotation in any given context is determined by ad-hoc rules, and they are inconsistent.

---

```
1 alias F = inout(int)* delegate(inout int);  
2  
3 F id(F dg) => dg;  
4 auto dg = id((immutable int)=>new immutable(int)); // error
```

---

## inout qualifier (cont.)

Furthermore, `inout`-qualified data cannot be stored in aggregates.

---

```
1 auto foo(inout(int)* p){
2     struct S{
3         inout(int)* p;
4     }
5     auto s = S(p);
6     // ...
7 }
```

---

Among other things, this means `inout` is incompatible with most of the Phobos range API. It permits zero data abstraction.

## Breaking `inout`: First try

Observations:

- ▶ Nested functions share `inout` with their enclosing function (if any).
- ▶ Higher-order functions within return types have their own `inout`.

This is inconsistent! However, the obvious way to exploit it has been patched:



## Breaking inout: First try

Observations:

- ▶ Nested functions share `inout` with their enclosing function (if any).
- ▶ Higher-order functions within return types have their own `inout`.

This is inconsistent! However, the obvious way to exploit it has been patched:

---

```
1  inout(int)* delegate(inout(int)*) foo(inout(int)* x){
2      inout(int)* bar(inout(int)* y){ return x; }
3      return &bar; // note: ok. 8)
4  }
5  void main(){
6      pragma(msg, typeof(&foo));
7      //inout(int)* delegate(inout(int)*) function(inout(int)* x)
8
9      int x=2;
10     pragma(msg, typeof(foo(&x)));
11     //const(int)* delegate(const(int)*)      (!)
12 }
```

---

## NB: The generic templated identity function

---

```
1 T id(T)(T arg) => arg;
2 // clearly, this will be true for all T:
3 enum preservesType(T) = is(typeof(id(T.init))==T);
```

---

## NB: The generic templated identity function

---

```
1 T id(T)(T arg) => arg;
2 // clearly, this will be true for all T:
3 enum preservesType(T) = is(typeof(id(T.init))==T);
```

---

Not so fast! Ironically, an effort targeted towards preserving qualifiers through an identity function broke the basic property that an identity function should preserve the type.

---

```
1 alias T = inout(inout(int)* delegate(inout(int)*));
2 static assert(preservesType!T); // fails!
```

---

# Circumventing the patchwork

---

```
1 @safe:
2 int a;
3 immutable(int) b=2;
4
5 auto foo(inout(int)* y){
6     inout(int)* bar(inout(int)* p){
7         return y;
8     }
9     return ()=>&bar;
10 }
11 void main(){
12     int* y=foo(&b)(&a);
13     *y=3;
14     assert(&b is y); // passes. ouch.
15     assert(b is *&b); // fails!
16 }
```

---

## return parameter attribute

---

```
1 ref int foo(return ref x) => x;
```

---

The `return` attribute has some similarities to `inout`:

- ▶ Interaction with nested and higher-order functions seems a bit tricky.
- ▶ `return scope` pointers and `return references` cannot be individually stored as struct fields.
- ▶ As there is only one name for a `return` attribute, lifetimes tend to get conflated.

However, as it does not require substitution in the result type and `return scope` can be pushed up `structs`, `return` avoids some `inout` pitfalls.

## Qualifier Polymorphism (Suggested Extension)

A good way to express this kind of thing would be *polymorphism*. E.g., instead of having only one name `inout`, add an explicit polymorphic parameter:

---

```
1 qual(int)* id[mutability qual](qual(int)* p)=>p;
2 // still works the same with higher-order functions:
3 qual(int)* delegate(qual(int)*
4 id[mutability qual](
5   qual(int)* delegate(qual(int)*) dg
6 ){
7   return dg;
8 }
9 // can easily express case where argument is polymorphic:
10 qual1(int)* delegate[mutability qual1](qual1(int)*
11 id(
12   qual2(int)* delegate[mutability qual2](qual2(int)*) p
13 ){
14   return p;
15 }
```

# Effect Polymorphism (Suggested Extension)

---

```
1 alias ComposeType =
2   int delegate(int)eff
3     delegate[effect eff](
4       int delegate(int)eff,
5       int delegate(int)eff,
6     )@safe pure nothrow @nogc;
7
8 ComposeType compose = [effect eff](
9   int delegate(int)eff a,
10  int delegate(int)eff b,
11 )@safe pure nothrow @nogc{
12   return x=>a(b(x));
13 };
```

---

# Effect Polymorphism (Suggested Extension)

---

```
1 class ASTNode{
2   int compImpl[effect e](scope int delegate(ASTNode)e dg){
3     return dg(this);
4   }
5   auto components()return scope{
6     struct Components{
7       ASTNode self;
8       int opApply[effect e](scope int delegate(ASTNode)e dg){
9         return self.compImpl(dg);
10      }
11    }
12    return Components(this);
13  }
14 }
```

---



# CTFE

- ▶ CTFE semantics technically part of the type system.
- ▶ But CTFE functions cannot manipulate types directly.
- ▶ Should probably be fixed.

# Forward references and introspection

---

```
1 static if(!is(typeof(x))) enum x = 2;
```

---

# Forward references and introspection

---

```
1 static if(!is(typeof(x))) enum x = 2;
```

---

```
1 static if(is(typeof(y))) enum x = 2;  
2 static if(!is(typeof(x))) enum y = 2;
```

---

# Forward references and introspection

---

```
1 static if(!is(typeof(x))) enum x = 2;
```

---

```
1 static if(is(typeof(y))) enum x = 2;  
2 static if(!is(typeof(x))) enum y = 2;
```

---

```
1 static if(!is(typeof(x))) enum y = 2;  
2 static if(!is(typeof(y))) enum x = 2;
```

---

# Dependency on compilation order

---

```
1 module a;  
2 import b;  
3 static if(!is(typeof(x))) enum y = 2;  
4 static if(is(typeof(y))) pragma(msg, "y defined");
```

---

## Dependency on compilation order

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2 import a;  
3 static if(!is(typeof(y))) enum x = 2;  
4 static if(is(typeof(x))) pragma(msg, "x defined");
```

---

```
1 $ dmd -o- a.d b.d  
2 x defined  
3 $ dmd -o- b.d a.d  
4 y defined
```

---

# Experimental frontend

- ▶ I partially built a D frontend with explicit dependency tracking



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# Experimental frontend

- ▶ I partially built a D frontend with explicit dependency tracking
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- ▶ It catches ambiguities and contradictions.
- ▶ It stopped compiling with DMD 2.061.

# Experimental frontend

- ▶ I partially built a D frontend with explicit dependency tracking
  - ▶ <https://github.com/tgehr/d-compiler>
- ▶ It catches ambiguities and contradictions.
- ▶ It stopped compiling with DMD 2.061.
- ▶ Ironically, the reason was going too crazy with code generation and introspection.

# TypeTuple AliasSeq

---

```
1 alias AliasSeq(T...) = T; // or 'import std.meta: AliasSeq;'
2 void main(){
3     AliasSeq!(int, int, int) s = AliasSeq!(1, 2, 3);
4
5     auto a = [s];
6     assert(a == [1, 2, 3]);
7
8     auto p = &s; // error
9
10    auto typeof(s) foo() => s; // error, cannot return sequence
11
12    int sum = s[0] + s[1] + s[2];
13 }
```

---

# Type Tuple AliasSeq

---

```
1 alias AliasSeq(T...)=T; // or 'import std.meta: AliasSeq;'  
2 void main(){  
3     AliasSeq!(int, int, int) s = AliasSeq!(1, 2, 3);  
4  
5     auto a = [s];  
6     assert(a == [1, 2, 3]);  
7  
8     auto p = &s; // error  
9  
10    auto typeof(s) foo()=>s; // error, cannot return sequence  
11  
12    int sum = s[0]+s[1]+s[2];  
13 }
```

---

- ▶ AliasSeq can contain arbitrary aliases
- ▶ If all are types, can use like a type, to declare multiple variables
- ▶ Metaprogramming tool

# Type Tuple AliasSeq

---

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13 }
```

---

- ▶ AliasSeq can contain arbitrary aliases
- ▶ If all are types, can use like a type, to declare multiple variables
- ▶ Metaprogramming tool

AliasSeq is not a tuple type. This is because it is not a type.

# What is a tuple?

- ▶ In general: Product type.
  - ▶ Aggregate of multiple values.
  - ▶ Can get back out whatever we stuck in.
  - ▶ Is no more than the sum [sic] of its parts.



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- ▶ Sounds a bit like `struct`.
- ▶ `std.typecons.tuple?`

Simplified:

---

```
1 struct Tuple(T...){
2   T expand;
3   alias T this;
4 }
5 auto tuple(T...)(T args)=>Tuple!T(args);
```

---

## What to use it for?

- ▶ Creating ad-hoc groupings when calling into generic code.
- ▶ For very localized data structures within a function or in small scripts.
- ▶ Returning multiple values.

# Tuples: What is missing?

Sticking things in.

---

```
1 auto foo(inout(int)* w){
2     auto t = tuple(w,w); // error
3     return t;
4 }
```

---

# Tuples: What is missing?

Getting things back out.

---

```
1 int* foo(return scope int* a){  
2   scope int* b = ...;  
3   scope t = tuple(a, b);  
4   return t[0]; // error  
5 }
```

---

# Tuples: What is missing?

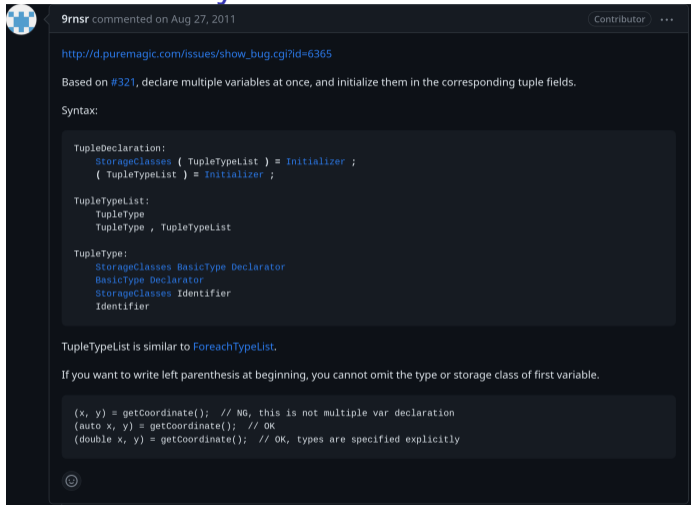
Destructuring.

---

```
1  import std.typecons: tuple;
2  auto t = tuple(1, tuple(2, 3));
3  auto (x, (y, z)) = t;
```

---

# A bit of History



9rnsr commented on Aug 27, 2011

[http://d.puremagic.com/issues/show\\_bug.cgi?id=6365](http://d.puremagic.com/issues/show_bug.cgi?id=6365)

Based on #321, declare multiple variables at once, and initialize them in the corresponding tuple fields.

Syntax:

```
TupleDeclaration:
  StorageClasses ( TupleTypeList ) = Initializer ;
  ( TupleTypeList ) = Initializer ;

TupleTypeList:
  TupleType
  TupleType , TupleTypeList

TupleType:
  StorageClasses BasicType Declarator
  BasicType Declarator
  StorageClasses Identifier
  Identifier
```

TupleTypeList is similar to [ForeachTypeList](#).

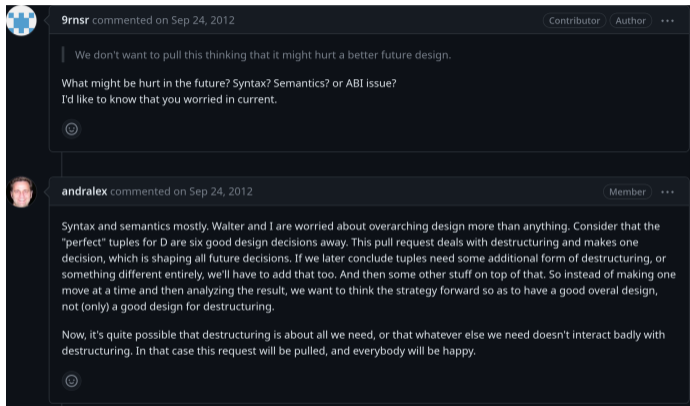
If you want to write left parenthesis at beginning, you cannot omit the type or storage class of first variable.

```
(x, y) = getCoordinate(); // NG, this is not multiple var declaration
(auto x, y) = getCoordinate(); // OK
(double x, y) = getCoordinate(); // OK, types are specified explicitly
```

<https://github.com/dlang/dmd/pull/341>

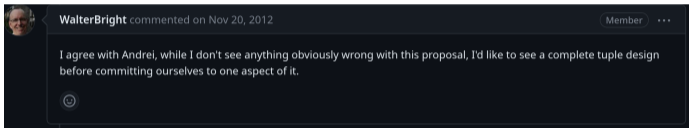


# A bit of History



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# What's wrong with this proposal?

---

```
1 auto (x, y) = tuple(1, "123");  
2 (int x, y) = tuple(1, "123");
```

---

# What's wrong with this proposal?

---

```
1 auto (x, y) = tuple(1, "123");  
2 (int x, y) = tuple(1, "123");
```

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- ▶ Looks a bit like it should mean: declare new `x`, assign to existing `y`.

# What's wrong with this proposal?

---

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2 (int x, y) = tuple(1, "123");
```

---

▶ Looks a bit like it should mean: declare new `x`, assign to existing `y`.

Otherwise: IMNSHO: Slightly generalize it and ship it.

---

```
1 auto (x, (y, z)) = tuple(1, "123");
```

---

## Slipped past Walter and Andrei

---

```
1 auto a = [tuple(1, "2"), tuple(3, "4"), tuple(4, "5")];
2 foreach(x, y; a) {
3     writeln(x, " ", y);
4 }
```

---

```
1 0 Tuple!(int, string)(1, "2")
2 1 Tuple!(int, string)(3, "4")
3 2 Tuple!(int, string)(4, "5")
```

---

# Slipped past Walter and Andrei

---

```
1 auto a = [tuple(1, "2"), tuple(3, "4"), tuple(4, "5")];
2 foreach(x, y; a.map!(x => x)) {
3   writeln(x, " ", y);
4 }
```

---

```
1 1 2
2 3 4
3 4 5
```

---

## Tuples: What is the hold-up?

- ▶ Benefit of `static foreach`: very small design space.
- ▶ In contrast, for “full tuple design”: many moving parts.
- ▶ Has to fit into existing language.
- ▶ Unfortunately, different syntax preferences exist.
  - ▶ Standard would be `(1, 2, 3)`.
    - ▶ Can be used soon, as comma operator is deprecated as an expression.
    - ▶ More tricky to integrate with function parameter lists.



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    - ▶ Clashed with delegates instead.
    - ▶ `{a, b} => a+b` syntax (matches single tuple)

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    - ▶ More tricky to integrate with function parameter lists.
  - ▶ DIP32 proposed `{1, 2, 3}`, to avoid comma operator clash.
    - ▶ Clashed with delegates instead.
    - ▶ `{a, b}` => `a+b` syntax (matches single tuple)
  - ▶ Some people want to reuse `[1, 2, 3]`.
    - ▶ A whole “unify tuples and arrays” discussion.
    - ▶ Does not work in D.
    - ▶ Static arrays are already built to interoperate with dynamic arrays.
    - ▶ Dynamic array are reference types.
    - ▶ Heterogeneous slices don't seem to make all that much sense.
    - ▶ Special case `void[]`, etc.
    - ▶ ...

# Quest for “full tuple design”

Decisions needed:

- ▶ How to unpack.
  - ▶ Syntax.
  - ▶ Lifetime issues.
    - ▶ Unpack by copy?
    - ▶ Unpack by move?

---

```
1 auto (a, b) = tuple(1, "2");
2 (int a, string b) = tuple(1, "2");
3
4 foreach((x, y); [tuple(1, "2"), tuple(3, "4"), tuple(5, "6")]){
5     writeln(x, " ", y);
6 }
```

---

```
1 auto (x, y) = (1, "2");
```

---

## Quest for “full tuple design”

Decisions needed:

- ▶ Where to unpack.
  - ▶ Local declarations
  - ▶ Assignments
  - ▶ `foreach`. Some baggage exists.
  - ▶ Function parameter lists.
    - ▶ Implicitly match top level as the parameter list?

---

```
1 int x = 1, y = 2;
2 (x, y) = (y, x);
3 assert((x, y) == (2, 1));
4
5 writeln(sum(zip(a,b).map!((x, y) => x*y))); // ?
6
7 writeln(sum(zip(a,b).map!(((x, y)) => x*y)));
```

---

```
1 auto (x, y) = (1, "2");
```

---

# Quest for “full tuple design”

Decisions needed:

- ▶ Currently, tuple indexing works via `alias this`.
- ▶ `static` `opIndex`?
- ▶ `static` `opSlice`?
  - ▶ Otherwise, `t[i..j]` is a sequence, not a tuple.
- ▶ `opCallRight` for unpacking?

---

```
1 auto (x, y) = (1, "2");
```

---

# Quest for “full tuple design”

Decisions needed:

- ▶ Tuple literals, tuple types.
- ▶ Named tuple components.
  - ▶ Interaction with named arguments.

---

```
1 auto (x, y) = (1, "2");
```

---

# Tuples: Suggestions

1. Fix tuple literal syntax. Ideally: `(1, 2, 3)` (or `[1, 2, 3]`, but tricky).
2. Finish tuple unpacking implementation, match tuple literal syntax.
  - ▶ `auto (x,y)= (1,2);`
  - ▶ In particular includes questions on lifetimes.
  - ▶ Seems tricky to avoid copies. Happy to chat about it.
3. Pull tuple unpacking ASAP.
4. Continue the bikeshedding on everything downstream from that.

# WIP tuple implementation

`github.com/tgehr/DIPs/blob/tuple-syntax/DIPs/DIP1xxx-tg.md`  
`https://github.com/tgehr/dmd/tree/tuple-syntax`

DIP and implementation still need updates.  
Help welcome!



# Hackathon projects

- ▶ Implement some of the suggestions from this talk.
- ▶ Improve type system soundness.
- ▶ Fix delegate context qualifiers.
- ▶ Work on tuple design.

Questions?