Value Lifetimes and Move Semantics DConf London '24

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- ▶ Some more of my ideas about how to evolve the language.
- ▶ Largely aspirational. (For reference, this is D 2.109.1.)
- ▶ You may however learn something about existing features and their limitations.
- \blacktriangleright If you'd like to contribute to D, maybe you'll find a project here.

Locations vs Values

Locations

▶ Heap locations.

Values

▶ A value is stored in one or more locations.

Lifetimes of Locations and Values

Location Lifetimes

- ▶ Stack. Nested.
- ▶ GC heap. Virtually infinite lifetime.
- \blacktriangleright Manual. E.g., malloc/free.

Value Lifetimes

- ▶ Delimited between constructor and destructor.
- ▶ May overlap arbitarily.

Copies vs Moves

Copies

```
▶ Default behavior, copied from C.
▶
```

```
1 auto a = b; // 'b' copied to 'a'
```
 2 writeln(a, " ", b); // can use both 'a' and 'b'

▶ New value is constructed to match old value.

Moves

▶ Currently:

```
1 auto a = move(b); // 'b moved to 'a'
```

```
2 writeln(a); // only supposed to use 'a' now
```
▶ Actually moves value of b into a and reinitializes b with init value.

NB. Constructors and destructors

```
1 struct Sf
2 ©disable this ():
3 this (int) { writeln ("S constructed") : }
4 ~ this () { writeln ("S destroyed ") ; }
5 }
6
7 void main () {
8 auto s = \text{immutable}(S)(0); // S constructed
9 // S live here
10 } // S destroyed
```
Limitations of constructors and destructors

- \blacktriangleright Seems kind of basic?
- ▶ Importantly: As far as I am aware, stack variables are always destroyed now though.
- \blacktriangleright However: The previous slide was still aspirational.

Constructors and type qualifiers

Stack variables can be accessed before being constructed:

```
1 @safe :
2 int[ immutable (int) *] cache ;
3 class Cf
4 immutable int x ;
5 \times void foo () {
6 if (kx \in k \cap \text{cache}) assert (\text{cache} [kx] == x); // fail
7 \quad \text{cache} [\& x] = x ;8 }
9 this (int x) {
10 foo ();
11 this x = x;
12 }
13 }
14 void main () {
15 auto c = new C(2);
16 c.foo();
\frac{17}{8}/33
```
Destructors and type qualifiers

```
1 int* pun(immutable(int)* q)@safe{
2 int *r;
3 struct S\{int * p:
 5 Cdisable this ();
 6 this (immutable (int) * p) immutable { this . p=p; }
7 \sim this () { r=p: }
8<br>9
9 \{auto s=immutable(S)(q); }\<br>10 return r:
     r return r :
11\frac{12}{13}void main ( ) @ safe {
14 immutable x=new immutable(int)(2);
15 in t \ast p=pun(x);
16 pragma(msg, typeof(x)); // immutable(int*)
17 writeln(**); // 2
18
     ∗p=3;
19 //assert(pis x);
20 writeln(*x); // 2
21 }
```
Destructors and type qualifiers

```
1 int* pun(immutable(int)* q)@safe{
2 int *r;
3 struct S\{int * p:
 5 Cdisable this ();
 6 this (immutable (int) * p) immutable { this . p=p; }
7 \sim this () { r=p: }
8<br>9
9 \{auto s=immutable(S)(q); }\<br>10 return r:
     r return r :
11\frac{12}{13}void main ( ) @ safe {
14 immutable x=new immutable(int)(2);
15 in t \ast p=pun(x);
16 pragma(msg, typeof(x)); // immutable(int*)
17 writeln(**); // 2
18
     ∗p=3;
19 assert (n \text{ is } x):
20 writeln(*x); //3
21 }
```
Total destruction

Stack variables can be destroyed without being constructed:

```
1 auto foo()2 \quad \text{int } x=2;
3 struct Tf
4 this (int) { writeln ("T constructed"); }
5 \rightarrow this () { writeln ("T destroyed: ", x): }
6 }
\tau return T(3);
8 }
9
10 struct S {
11 typeof (foo() ) t;
12 this (int)13 throw new Exception ("oops.");
t = f \circ \circ ():
15 }
16 }
```
Memory safety vs crash safety

Safety

- ▶ Safety means "bad things do not happen".
- \blacktriangleright Safety is often qualified.

Memory safety

- ▶ Memory safety means all behavior of a function is defined.
- ▶ Type safety: "Well-typed programs are memory safe."
- ▶ Languages like D or Rust are not type safe.
- ▶ Common aim: Conditional type safety.

Memory safety is a lowest-common denominator notion of safety, it is required for any other kind of safety. Memory unsafe programs often suffer from remote code execution exploits.

Dealing with unsoundness

- ▶ Good rule of thumb: If it is not formally verified, it is probably unsound.
- \blacktriangleright If it is formally verified, there is probably a bug in the specification.
- \blacktriangleright If there is no bug in the specification, there is probably still some other part of your system that is not formally verified.
- \blacktriangleright If your entire system is formally verified, there is still the possibility of holes in your formal system.
- ▶ Hence software licenses usually say "ABSOLUTELY NO WARRANTY OF FITNESS FOR ANY PARTICULAR PURPOSE".
- ▶ "Just don't write bugs" is a surprisingly common attitude, but delusional for basically any non-trivial system, without formal methods.
- ▶ Type systems are a lightweight form of formal methods that are widely deployed. Formally verifying them is consequential.

(Other type systems are unsound, too)

- ▶ Common misconception: @trusted means "memory unsafe, do not check this".
- ▶ The opposite is the case, it means "memory safe, but not checked".
- \blacktriangleright It is the *precondition* for D's aspired conditional type safety guarantee.
- ▶ The precondition is vacuously satisfied if you do not write @trusted code. Hence @safe yields a type safe subset of the language. (Aspirationally.)
- ▶ @live does not improve conditional type safety. It does not give additional safety guarantees for code that is already @safe.
- ▶ It may or may not help you with improving memory safety of a specific piece of @system/@trusted code. YMMV.
- \triangleright Consider it to be a linting tool helpful with a specific, restrictive way of writing code.
- ▶ This is not like Rust's borrow checker even though it technically checks borrows.
- ▶ May be a good basis for future type system extensions that do give conditional type safety guarantees.

Spreading a bit of GC FUD

(Live Demo.)

```
1 import std.stdio, std.random;<br>2
 3 struct S{
         ub y te [1024] payload;
 5 S
∗ n e x t ;
 \frac{6}{7}8 void main ( ) {
 9 S* head = new S;
\frac{10}{11}S* curr = head :
11 int i = 0;<br>12 for (:: i +)12 for (:; i++){<br>13 curr.next
13 curr.next = new S;<br>14 curr = curr.next:
14 curr = curr.next;<br>15 if (|(||^{6}41000000))if ( ! ( i %1000000)) writeln (curr);
\frac{16}{17}17 //writeln(*head);
18 }
```
Garbage collection is undecidable

- \blacktriangleright Technically, tracing GC is an approximate heuristic.
- \blacktriangleright It says data can be deallocated when it is no longer reachable.
- ▶ Actually, data can be deallocated when it will no longer be accessed.
- ▶ Compilers can and do sometimes optimize a program that has a memory leak to one that does not.
- ▶ The example program might blow up sporadically in a hard to explain way if a false pointer appears. (Less likely on 64 bit.)

Tracing GC

▶ In my experience: If I

▶ Use the GC.

 \blacktriangleright Do not use type qualifiers.

 \blacktriangleright Then memory safety is very rarely a concern.

▶ The main potential source of unsafety is escaping stack references.

Reasons to use @safe

▶ Therefore, I think the most important reasons to use @safe are:

- ▶ Simple: When working in a team, to ensure people use the language in the "simple" way, that is clearly type safe. (See Robert's "Simple @safe D" talk from DConf'23.)
- ▶ Expressive: Trying to do error-prone things like taking stack references and manually managing memory. While being drunk and/or tired. Without any worry it will cause a week-long debugging frenzy in front of the release deadline.
- \triangleright One of these is more interesting, but the other one is both easier and more important for getting taken seriously.

Are we type safe yet?

For the simple @safe D direction, I think we need:

- ▶ Initialization safety.
- \blacktriangleright Fully reliable stack reference detection. (E.g., slicing static arrays.) Maybe even promote them to the heap.
- ▶ A GC that works better both inside and outside of single-threaded batch programs (thanks Steven/Amaury!)
- ▶ Find a way to deal with inout.
- \blacktriangleright Fix type checking for qualified delegate contexts.
- \blacktriangleright Fix closure allocation in loops.
- ▶ Think about ways to validate DMD against a formally-verified implementation of the fully lowered D subset. E.g., guided test case generation.
- \blacktriangleright Fix all the other bugs.

Are we expressive yet?

For the expressive direction, I think DIP1000 has significant limitations while also being quite confusing at first. Probably we can find a better tradeoff. Things to explore:

- ▶ Move semantics. (DIP1040)
- ▶ Move constructors. (DIP1040)
- ▶ Escape checking for non-nested lifetimes.
- \blacktriangleright Multiple indirections.
- \triangleright Effect polymorphism. (Dennis had to break the type system!)
- ▶ Attribute inference for recursive functions (hard).
- ▶ Or even just conditional attributes?
- Better escape analysis in the frontend.
- ▶ @nogc exceptions. (DIP1008)
- \triangleright Ownership/isolated.

Working with what we have

- ▶ "One indirection ought to be enough for anyone". Tuple of arrays.
- ▶ @system fields.
- ▶ Fake stack references. (E.g., Dennis' arena design)
- ▶ Runtime checks instead of or to complement type system features.
	- ▶ After all, range checks are how we took care of buffer overruns. We can also do this for use after free.
- \triangleright scope/pure/static callbacks with DIP1000.
	- 1 smartPointer.access!((ref x){ smartPointer=other }); // runtime crash

Benefits of runtime checks

▶ Typically much more precise.

```
1 auto v = vectorFrom(1, 2, 3);
2 \quad \text{assert}(i != j);\frac{3}{3} scope x = \& v[i]; // returns by reference
4 scope y = \& v[i]; // type systems likely to reject this
5 * x = 2;
6 * v = 3;
```

```
1 auto v = vectorFrom(1, 2, 3);<br>2 assert (i!=j);
 2 assert (i != j);<br>3 // if we do n
 3 // if we do not allow aliases, v only has to count borrows<br>4 scope x = v. borrow(i):
 4 scope x = v \cdot \text{borrow}(i);<br>5 scope v = v \cdot \text{horrow}(i):
           scope y = y. borrow (i);
 \frac{6}{7}7 // even aliasing can in principle be allowed<br>8 // at the cost of higher auxiliary memory us
 8 // at the cost of higher auxiliary memory usage<br>9 // scope z = v.borrow(i):
           // scope z = v. borrow (i);
\frac{10}{11}11 x \cdot \arccess ! ((ref int x) { x=2; });<br>12 y = 2: // syntax sugar for the
           v = 2: // syntax sugar for the above pattern
\frac{13}{14}11 \text{ y} -=2: 11 \text{ would crash at runtime}15
16 v.\text{return } (x);<br>17 v.\text{return } (v):v. return(v):
18
19 // ok, nothing borrowed out, reallocation would be safe<br>20 v = 2.
           v \sim 2;
```
▶ Not safe against crashes. Requires storing additional data to check time-dependent properties. "Time range check."

DIP 1040

DIP1040 by Max Haughton and Walter Bright. Post community round 1.

▶ DIP1040 proposes to move the static last use of a variable:

DIP 1040

 \triangleright Can disable the copy constructor to force moves:

```
1 struct Sf
2 this (int x) { ... }3 Odisable S(ref S other); // copy constructor
4 S(S other) { ... } // move constructor (also DIP1040)
5 }
6
7 auto a = S(2);
s auto b = a; // ok, a is moved
9 auto c = b; // ok, b is moved
10
11 auto x = S(2);
12 auto y = x; // error: x is copied
13 auto z = x;
```
Potentially, DIP1040 is a big step up for the usability of move-only types.

Move-only types

Move-only types can support:

- ▶ Value-type-like referential transparency.
- \blacktriangleright Efficient mutable updates.
- \blacktriangleright No implicit costly duplication.
- \blacktriangleright They behave like resources.
- ▶ D essentially supports substructural typing via *@disable* of special member functions.

Move constructors

```
1 struct Sf
2 \quad \text{this (S other)} \{ \dots \}3 }
```
- \blacktriangleright Structs in D are always implicitly moveable.
- ▶ Without a move constructor, this means structs cannot have internal references.
- \blacktriangleright This has implications for expressiveness and $C++$ interoperability.
- ▶ Move constructors

Danger: Implicit destructor elision

In DIP1040, the move constructor implicitly passes by ref :

```
1 struct Sf
2 private @system int* x ;
3 T t;
4 ...
5 ~ this () @trusted {
6 if(x) free (x);
7 \times = null;8 }
9
10 // implicitly S(ref other), but recorded as move
        constructor :
11 S(S other) Otrusted {
12 this x=other . x;
13 other.x=null;
14 this t = other. t; // copy
15 }
16 }
```
Tweaking DIP1040

```
1 struct S(T) {
2 this (T) (T \text{ arg}) \{ ... \}3 }
```
▶ Destructor elision is very dangerous.

- ▶ Might implicitly break RAII.
- ▶ Can cause memory leaks.
- ▶ Better approach: Destructor elision should be explicit.
- \blacktriangleright Also useful for unpacking.

Not addressed by DIP1040

▶ How to force a move?

- \blacktriangleright How to move the receiver of a method call?
- ▶ How to move a container into a range into an iteration over the range?
- \blacktriangleright Unpacking/destructuring without copies.
- \blacktriangleright How to avoid reinitialization with init?
	- ▶ Needed to make private @system destructors useful.
- ▶ Reinitialization.
- \blacktriangleright Reinitialization with a different type (strong updates).
- \blacktriangleright Non-lexical variable lifetimes.

Thanks!

Questions?