

## We need a new GC

Advancing GC technology for D into the modern age

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## The current GC is not state of the art

- The current GC is based on mostly the same code that was present in D1/Tango
- We have had several improvements:
	- $\circ$  Precise scanning no longer as important with 64-bit addressing
	- Forked scanner Optional performance improvement, but still from Sociomantic days
	- Multi-threaded scanner Default scanner, Utilizes CPU more efficiently
- Scanner is not optimized for today's architectures
	- Binary search for blocks
	- Too many touches of various pages per mark
	- Does not take enough advantage of modern addressing
	- Does not try to reduce TLB pressure

## Implementation limitations

- All allocations are done from a global structure
- A global lock protects threads from invalidating memory allocation
	- No allocations while collecting
- All threads must be stopped during scanning (except for forking collector)
	- Fork creates a write barrier on all memory to perform COW functionality.
- Implementation is tied to druntime
	- All type data is fetched via TypeInfo
	- Array runtime is dependent on implementation details of GC

## Replacing C allocator with our allocator – in user code

- Many people use the C allocator as a "faster" allocator.
	- But you still have to pin the memory if it might contain pointers, or you might accidentally free something.
- D's allocator should be just as fast, and performant.
- std.container.array.Array
	- $\circ$  Allocate with C malloc, pin in the GC Shouldn't be necessary!
- std.typecons.refCounted
	- $\circ$  Allocate with C malloc, pin in the GC Shouldn't be necessary!
- std.stdio.File
	- $\circ$  Allocate with C malloc, pin in the GC you know the drill.

## Only advanced features for 64-bit arch

Our GC takes advantage of 64 bit addressing

- All current archs use only 48 bits for addressing (256TB of address space)
- Using memory mapping, we can plan out how memory is laid out to take advantage of hardware architecture
- We can use sparse data structure
	- Uses a lot of address space, but most of it is virtual zeros

## How memory HW and OS work



#### Page Table



## Transparent Huge pages

- Huge pages (2MB, 1GB) are profitable because one entry in the TLB maps to more memory.
	- TLB space is finite, we can cache more memory in less space.
	- Temeraire shows that this is very profitable for programs using a lot of RAM.
- We try to cluster allocation on aligned 2MB blocks.
- When enough consecutive 4k pages are used to form a 2MB huge page, the OS can swap these pages for a huge one transparently.

## All zero memory page table

- Each level points to the same next level page
- All pages point to a read-only zero page the kernel uses for all processes
- Entire memory can be described using 4 4KB pages



## Add one page that is not zero

- Level 0 always one page
- Most entries still point to zero page
- Only one path leads to the non-zero page
- More efficient to keep modified pages together



# How the new GC Works

Part 1: Large allocations

## Use own mutex to avoid initialization or allocation

- We want our mutex implementation to never allocate.
	- For obvious reason, this would be a problem within the GC.
- We want all zero to be a valid state for the mutex.
	- We want to use virtual zeros to provision static data structures that will only be materialized if used.
	- Some data structures in the allocator need mutexes, so all zero mutexes need to be valid.
- When not contended, atomic operations are enough to take/release the mutex.
- Under contention, if a thread needs to be paused, we the kernel's futex API.

## Region allocator

- Responsible for getting address space from the OS
- Requests allocations of 1GB at a time
	- All memory requests from OS are virtual all-zero pages
- Track ranges of memory that are not used in a Red-black tree
- 2 regions one for pointer-containing blocks, one for non-pointer blocks
- Region allocator provides chunks of memory in 2MB blocks

## Blocks: 2MB pages

- Blocks are managed by a Page Filler
- Requested from the appropriate region allocator, keeping pointer-containing blocks separate from pointer-free blocks
- Tracked in heaps ordered by longest-free-range and number of allocations
- Heaps divided into small allocation heaps, and large allocation.
	- Track which heaps have any available blocks.
	- Only 32 heaps, so constant bitmask operation to find best non-empty heap
	- Heaps operations take amortized constant time
- Selecting the block to use takes amortized constant time

## Metadata Tracking

- Some allocations dedicated to tracking metadata about all allocated memory
- BlockDescriptor
	- Keeps track of allocated pages (which ones, and how many)
	- Remembers the longest free page run
	- Allocation class (which bucket of longest free range)
	- How many allocations in the block
	- Dirty pages (which ones, and how many)
	- Generation (to help keep descriptors close together)
- All metadata is allocated outside normal allocation path, never freed
- Unused metadata goes into a heap (ordered by generation/address)

## Pairing heap data structure

- Standard heap with N children per node
- When inserting a new child:
	- Better than the root? It becomes the new root
	- Worse than the root? It goes into an auxiliary heap
- Whenever a child is added to the auxiliary heap:
	- $\circ$  If count(Heap<sub>aux</sub>) is even, perform N merges, where N is the number of trailing zeros
	- In practice, this amortizes to 1 merge per insertion.
- When removing the root:
	- Perform a merge on the root's children (generally 1-2 children)
	- Perform a merge of the new root with the aux list root

## Pairing Heap Demo!

## Allocation classes

- We bucket allocation sizes (in pages) in classes.
- $\bullet$  Growth rate from one class to the next must be
	- Greater than 1 (or it doesn't grow)
	- Smaller than φ, the golden ratio, to ensure that space left behind can eventually be reused.
- We settled on size classes with two bits of precision.
	- Each time we use one more bit, we grow the step between classes.
	- $\circ$  1, 2, 3, 4, 5, 6, 7, 8
	- $\circ$  10, 12, 14, 16
	- $\circ$  20, 24, 28, 32,
	- $\circ$  40, 48, 56, 64
	- 80, 96, 112, 128
	- 160, 192, 224, 256
	- 320, 384, 448, 512 (empty block, we release it to the region allocator).
- In total, 31 allocations classes are used.

## Page Filler

- The page filler gets blocks from the region allocator and allocates pages out of them.
- There are 4096 pre allocated page filler as static data.
	- The initial state of a page filler is all zeros, so it doesn't use any actual memory.
	- The page filler is selected based on the core the the thread runs on.
		- This ensures no contention, unless the OS reschedules the thread mid allocation.
	- When a new page filler is used, the OS automatically provides memory for it.
- The page filler maintains a set of heaps of blocks for each allocation class.
	- Favor blocks with shorter free ranges to give the larger runs the opportunity to grow.
	- Favor blocks with fewer allocations as they are more likely to be freed.





## Large allocations

- Large allocations are done at a page granularity.
- They are used when allocating > 14kB
- The allocation class required is computed and the correct heap selected
	- This creates some slack. This on purpose. Preferring best fit tends to create more very small runs than the application demands.
	- For instance, a 21 page allocation will look into buckets starting with the 24 pages one.

## Large allocation: Extent

- An extent tracks an allocation of any number of pages (page-level granularity).
- Allocations less than 2MB are allocated using the Page Filler heaps, finding the best matching block
- An extent "descriptor" uses 128 bytes to describe everything about a large allocation.
	- Allocated and never freed, like Block Descriptors

## Huge allocations

- Allocations larger than 2MB, requests consecutive new blocks from the page filler
- Last page can be filled with other smaller allocations if there is room.
- Should be deprioritized for filling, as freeing one large allocation can return a large amount of used memory to the system.

## Reverse lookup of allocations

- When allocating, we maintain a 2 level radix tree for reverse lookup.
- Level 1 is a 2MB buffer of static data filled with virtual zeros containing pointers to the next level in the radix tree.
- Level 2 is made of 2MB buffers containing pointer size page descriptor, that contain information about what's allocated on a given page.
- The whole data structure is lock free and can be accessed by multiple threads at once.

#### Extent Map (2-level Radix Tree)





## Page descriptor

Information about the allocation behind a pointer

#### Page Descriptor (64 bits)



## Procedure to free large allocations

- Use the radix tree to find the extent, the block and the page filler.
- Clear the page descriptor from the radix tree.
- Remove the block from its heap in the page filler.
- Free the pages in the block, and recompute associated metadata.
- Reinsert the block in the appropriate heap, or release it to the region allocator if it is now empty.

### Part 1: The end



# We need a new GC Episode II

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## How the new GC Works

Small allocations

## Size classes

- Similar to allocation classes used for blocks.
- Uses 2 bits of precision for a total of 38 size classes.
	- 8, 16, 24, 32, 40, 48, 56, 64
	- 80, 96, 112, 128
	- 160, 192, 224, 256
	- 320, 384, 448, 512
	- …
	- 10240, 12288, 14336
- Balances internal fragmentation (space lost due to requested size not matching the size class) and external fragmentation (empty slot in slabs due to insufficient demand).
- $\bullet$  Extent class is 0 for large, otherwise, size class  $+1$
- <https://github.com/snazzy-d/sdc/blob/master/docs/sizeclass.md>

## Slab

- A slab is a special kind of Extent that contains several small allocations.
- It also contains a bit field to know which slots are allocated.
- If slot count allows for it, we have another bit field to know whether a slot has associated metadata (append support, finalizer).
- Slab with more than 16 slots are considered "dense" other are "sparse".
	- $\circ$  A slab with 16+ elements is likely to be long lived or immortal.
	- Dense slabs are allocated on their own set of blocks.
	- Sparse slabs are mixed with large allocations.
- Slabs are allocated from the Page Filler, just like large allocations are.

## Arena and Bins

- There are 4096 pre allocated arenas with virtual zeros. They contain:
	- One bin per small size class.
	- A Page Filler.
- When needed an arena, and it's page filler, is picked based on the CPU core used by the thread.
	- This ensures no contention unless the OS reschedule the thread mid allocation.
- Each bin contain a heap of the slabs for a given size class which are not completely full.

#### Arena





## Page descriptor

Information about the allocation behind a pointer

#### Page Descriptor (64 bits)



### Find the index of an allocation in a slab

- For each size class, we precompute M and s such as M /  $2^s \approx 1$  / size
	- We chose M and s such as rounding works out for any possible offset in a slab.

```
auto computeIndex(void* ptr, PageDescriptor pd) {
   auto page = alignDown(ptr, PageSize);
  auto slab = page - pd.index * PageSize;
  auto offset = ptr - slab;
   auto b = binInfos[pd.sizeClass];
  return (offset * b.multiplier) >> b.shift;
}
```
### Thread cache

- Each thread has a Thread Cache living in thread local storage.
- The thread cache contains a bin for each small size class.

- When allocating, we look into the cache first.
	- If there isn't a suitable element, we refill the cache via the arena.
- When freeing, we try to put the element back into the cache.
	- $\circ$  If the cache is full, then we flush it to the bin.

• Batching operations in the arena ensure fast operations most of the time.



## Thread bin management

- Periodically, we "recycle" a bin.
	- If we refilled the bin since last time, we increase the batch size for that size class.
	- $\circ$  If the low water mark didn't reach 0, we flush some of the elements and reduce the batch size.
- At the end of the recycling process, we reset the low water mark for the bin.
	- When we allocate from the bin and are at the low water level, we reduce it.
- This process ensures that the usage of the thread cache adapts to the behavior of the application at run time.
- Elements in the thread cache appear to be allocated from the perspective of the rest of the GC.

## Thread Bin



## Fast path touches very few pages

- The data about the thread bins are all kept together. If there is a suitable element in them, pick it, return, done.
- That's only 1 page touched for the allocation fast path!
- We cache entries for the first level of the radix tree in the thread cache.
	- We cannot skip the last level lookup.
	- But we end up staying in the thread cache for the first level most of the time.
	- The cache has 24 entries, which maps to 24GB of address space. If your thread has more than that that is very hot, then what are you doing?
- Then, if there is room, we put the pointer back in the thread bin.
- That's only 2 pages touched when freeing on the happy path!

## How the new GC Works

Appending and finalization

## Appendable and finalizers

- Allocations/arrays might need to be finalized
- Appending to an array should grow in the allocation if possible
- $\bullet$  Need to store a finalizer and a "used" size.
- Druntime always stores these in the allocated space.
- New GC stores data based on the size of the allocation.

## Appendable and finalizers

- Large allocations are easy
	- Plenty of space in the Extent record itself, most GC metadata not needed (marking bits, etc.)
	- Store finalizer, used size directly in the Extent
	- Can extend a large Extent without having to touch allocated memory.
- Slabs do not have enough space in the extent to store a pointer per slot
	- 8 bytes needed to store finalizer pointer
	- Store this inside the allocation at the end
	- $\circ$  8-byte allocations are never appendable always reallocate.
- Store "unused" space instead of "used" space.
	- The more space used, the less space we need to store the size.
	- Can fill up the entire allocation, just remove the metadata

### Appendable and finalizers - slab metadata

- Max alloc size for slabs is 14336 only requires 14 bits for "unused" space
- We have 16 free bits in the finalizer pointer! Stuff it in there.
- Set a bit in the Slab Extent to flag which slots have metadata
- With Finalizer present, must always use all 8 bytes
- Without Finalizer present, can use one or two bytes for "unused" space
- $\bullet$  2 flags to determine what state we have  $-$  14 bits  $+$  2 bits for flags.







Loaded in Register (Little Endian)



## Finalizing an allocation

- If metadata is present, and finalizer not null, pass finalizer and used size into handler function
- SDC handler just calls the finalizer with the pointer and valid size
- Druntime hook must do something different (that pesky TypeInfo...)

## How the new GC Works

Garbage Collection

## Garbage collection

- The GC uses stop the world, parallel, mark & sweep garbage collection.
- The thread invoking the collection process stops all other threads.
- Some preparatory work is done, such as allocating buffers for mark bits.
- Several worker threads are started and marking process begins.
- We then go over all the initialized arenas, go over all blocks, and free all unmarked allocations.

• All in all, fairly standard mark and sweep stuff!

## Stopping the world

- We hijack pthread create to register all threads in the GC and setup signal handling.
- We send SIGPWR to suspend a thread, SIGXCPU to resume.
	- These signals have been used by Boehm for a long time so we assume they are a "de facto" standard.
- We do not want to suspend a thread in a middle of a complex operation.
	- Druntime solves this with a global lock, but we do not want that either.
	- We introduced a busy state to thread where they cannot be suspended.
- When threads aren't busy, the signal handler for SIGPWR simply uses sigsuspend to wait for SIGXCPU
	- Because we use SA SIGINFO, the CPU state has been pushed on the stack so we can scan as this.

## Hijacking pthread\_create to register threads

- We define our own pthread create function in the GC. The linker picks this one over the system's.
- This function does the preparatory work for the thread to be initialized properly for the GC to manage.
- It then calls a trampoline (function pointer) initialized to do the following:
	- Resolve the system's pthread create using dlsym.
	- Redefine the trampoline with the system's pthread create.
	- Forward the call to the system's pthread create.

## Busy state

- When doing critical operation that cannot be suspended, the thread enters the "busy" state.
- When the signal to suspend is received by a busy thread, the signal handler sets the thread for delayed suspension and resume execution immediately.
- When the busy state is exited, the thread checks if delayed suspension was requested.
	- If so, the thread pushes the CPU state on the stack and suspends itself using sigsuspend.
- More complex in practice: this has race conditions galore.
- But we can prevent thread suspension at an undesirable time without any kind of locking mechanism!

## Mark phase: Overview

- One thread is created for each core on the machine.
- Thread wait for work to be put on a worklist. Work consist in a range of memory to scan for pointers.
- The main thread start feeding the worklist with global segment, suspend thread's stack, and various other roots, then wait itself on the worklist.
- When the worklist is empty, and all other threads ran out of work, the thread returns.
- By that time, every alive allocation is marked.

### Mark phase: Worker threads

- When the worker's worklist is empty, it picks 1 range on the shared worklist.
- The worker then goes over each potential pointers in the range.
	- It first does a bound check to see if it is in the range of heap addresses.
	- $\circ$  If it is, it does a lookup in the Extent map to find what's there.
	- If there is a hit, the worker marks the allocation.
- After marking, if an allocation contains pointers, the worker will add it:
	- $\circ$  If its worklist is empty, it add the range in it.
	- For large allocations, it adds the new range to the shared worklist.
	- For small allocations, it add the new range to its own worklist. This allows the worker to blast through graphs of small objects.
	- If the worker's worklist grows bigger than 16 elements, it gets partially flushed in the shared worklist.

## Sweep phase

- We go over all initialized arenas, over all blocks in these arenas, and over all extents in these blocks.
- We free all the allocations which are not marked.
	- If they have one, we run the finalizer.
- If the block is now empty, we give it back to the region allocator.
- If the block contain more than 16 dirty pages, we purge unused pages from the block.
	- They turn back into virtual zeros.

• Good job! Now we can restart the world!

## Druntime Integration Getting SDC and DMD to play nice

## Hooking SDC GC from Druntime is… complicated

- SDC GC does not have access to druntime
- No understanding of TypeInfo
- Supplies its own scheme for array metadata/finalizers
- qalloc function returns implementation details of the Druntime GC, but is a public interface
- Odd API functions required (e.g. collectNoStack)
- SDC ABI is different from DMD's!

## Migrate Druntime array runtime into GC

- How to manage array "used" size is now GC dependent must now ask the GC to do all the work.
- New type ArrayMetadata which becomes the interface to update the array used size.

```
struct ArrayMetadata {
     ... // private fields
     void *base();
     size_t size();
     size_t _gc_private_flags(); // GC specific flags
     bool setUsed(size_t used, size_t existingUsed = ~0UL);
     bool contains(void *ptr) const @trusted;
}
```
## Remove implementation details from interface

- GC interface functions accept TypeInfo
- DRuntime GC malloc uses TypeInfo for precise scanning bitmap and calling finalizer
- Nothing else effectively uses TypeInfo, even if it is passed
	- For example, extend accepts TypeInfo but ignores it
- But all allocation hooks are now templates!
	- Extract the pointer bitmap from the compiler, pass it directly. We can eliminate RTInfo.
	- Have a generic callback data pointer for finalization. But we still use TypeInfo here
- Deprecate galloc function. ArrayMetadata is now the API for arrays.
- STRUCT FINAL bit no longer part of API, but used internally by Druntime.

## Miscellaneous hook problems

- $\bullet$  Most must be extern(C) to be ABI compatible
- GC is not directly referenced from code, so there must be a trick reference to avoid the linker from pruning it.
- Had to add some extra hooks to druntime (e.g. pre/post stop the world) to implement proper thread stopping from SDC
- Class finalization does not fit with SDC scheme the finalizer pointer is part of the classinfo at the front. So we store a "finalizer" of cast(void\*)1

## Future Possibilities

What else can we pile on?

## Bohem's short pauses.

- During the mark phase, add write barriers over the allocations that contain pointers.
	- This can be done making them write protected with mprotect
	- Alternatively, we can use the dirty bits the CPU fill for us in the page table, but OS API to access these are especially bad and high overhead.
- Stop the world.
- Rerun a mark phase, using the dirty pages as a starting point.
	- This is typically very short, because almost everything alive is already marked.
- Resume the world, collect.

## Replacing C allocator with our allocator – for all code

- C code in pre-built libraries would now also allocate using the GC
- Theoretically, you would no longer have to worry about pinning memory you are passing to a C function to keep.
- Still experimental, does not work properly when combined with Druntime.

### Miscellaneous items

- PRs for DMD to enable a dub package to try the GC.
- Support more platforms (Windows and OSX are priorities).
- Tweak heuristics based on real world feedback.
- Telemetry and other statistics.

### Part 2: The end

